**ASSIGNMENT-4**

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# QUESTION:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

# CODE:

#include <WiFi.h> #include <PubSubClient.h> #define TRIGGER 2

#define ECHO 15

#define sound\_speed 0.034 int distance;

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength);

#define ORG "wp72r7"

#define DEVICE\_TYPE "iot-device-1" #define DEVICE\_ID "123456789"

#define TOKEN "987654321"

String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-2/evt/Data/fmt/json";

char subscribetopic[] = "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback ,wifiClient); void setup()

{

**Serial**.begin(115200); pinMode(TRIGGER, OUTPUT); pinMode(ECHO, INPUT); delay(10);

**Serial**.println(); wificonnect();

mqttconnect();

}

void loop()

{

digitalWrite(TRIGGER, HIGH); delayMicroseconds(10); digitalWrite(TRIGGER, LOW);

int duration=pulseIn(ECHO,HIGH); distance=(duration\*sound\_speed)/2; **Serial**.print("Distance:"); **Serial**.print(distance); **Serial**.println("cms"); if(distance<100){ PublishData(distance);

}

delay(1000);

if (!client.loop()) { mqttconnect();

}

}

void PublishData(int d) { mqttconnect();

String payload = "{\"message\":alert}";

**Serial**.print("Sending payload: ");

**Serial**.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) {

**Serial**.println("Publish ok");

} else {

**Serial**.println("Publish failed");

}

}

void mqttconnect() {

if (!client.connected()) { **Serial**.print("Reconnecting client to "); **Serial**.println(server);

while (!!!client.connect(clientId, authMethod, token)) {

**Serial**.print("."); delay(500);

}

initManagedDevice();

**Serial**.println();

}

}

void wificonnect()

{

**Serial**.println(); **Serial**.print("Connecting to ");

WiFi.begin("Wokwi-GUEST", "", 6);

while (WiFi.status() != WL\_CONNECTED) { delay(500);

**Serial**.print(".");

}

**Serial**.println(""); **Serial**.println("WiFi connected"); **Serial**.println("IP address: "); **Serial**.println(WiFi.localIP());

}

void initManagedDevice() {

if (client.subscribe(subscribetopic)) { **Serial**.println((subscribetopic)); **Serial**.println("subscribe to cmd OK");

} else {

**Serial**.println("subscribe to cmd FAILED");

}

}

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength)

{

**Serial**.print("callback invoked for topic: ");

**Serial**.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) { data3 += (char)payload[i];

}

**Serial**.println("data: "+ data3); data3="";

}

**OUTPUT:**

